

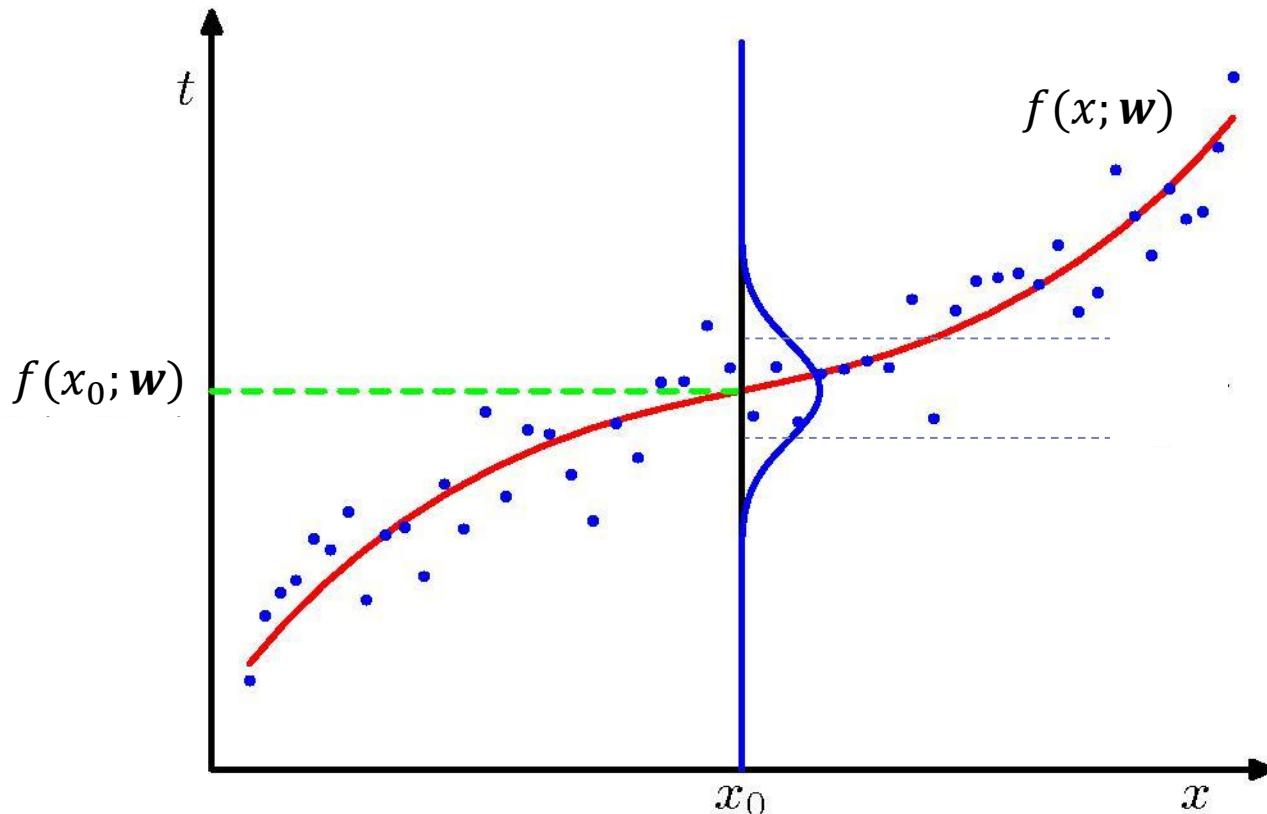
# Regression and generalization

CE-717: Machine Learning  
Sharif University of Technology

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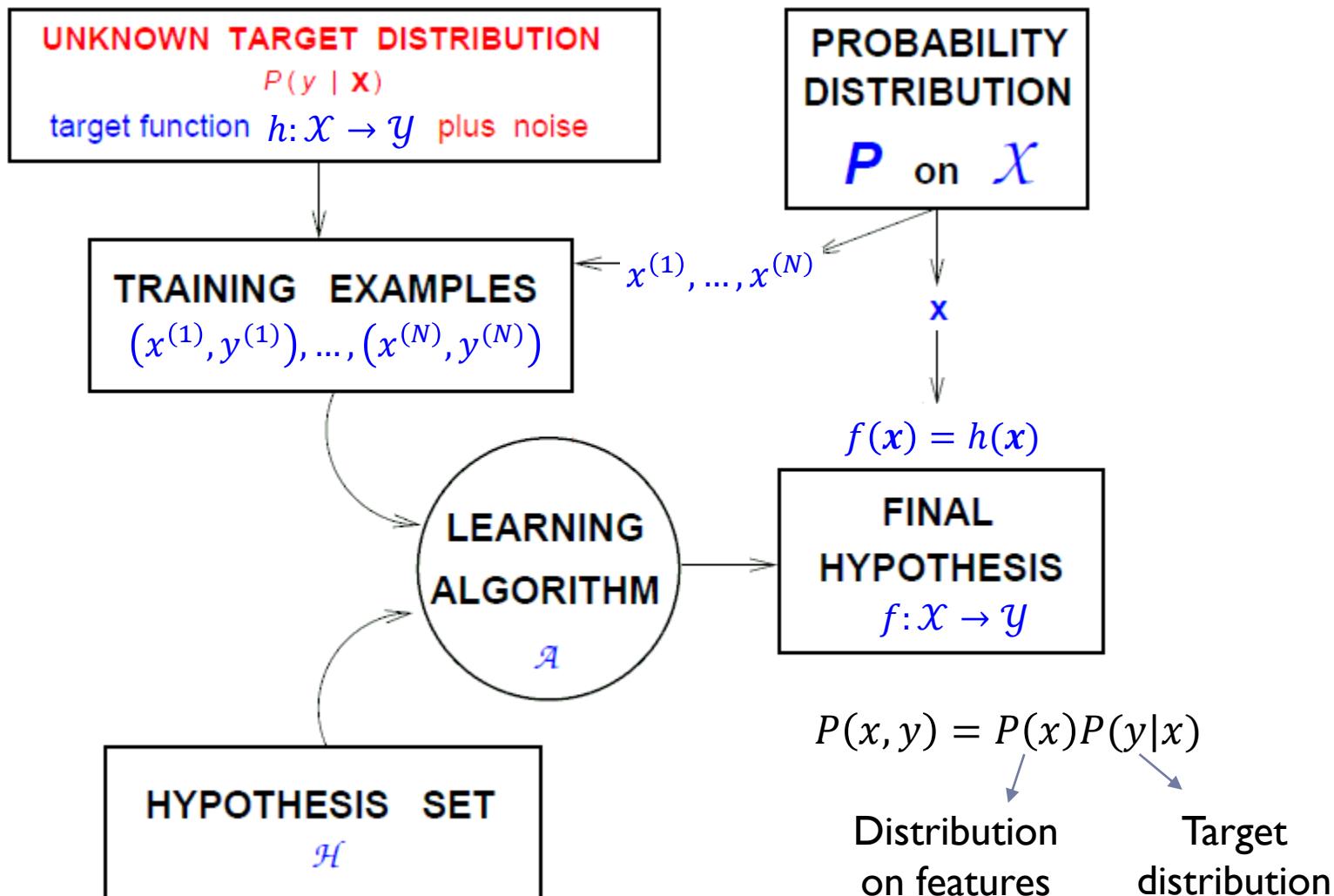
# Curve fitting: probabilistic perspective

- ▶ Describing uncertainty over value of target variable as a probability distribution
- ▶ Example:



# The learning diagram including noisy target

► Type



# Curve fitting: probabilistic perspective (Example)

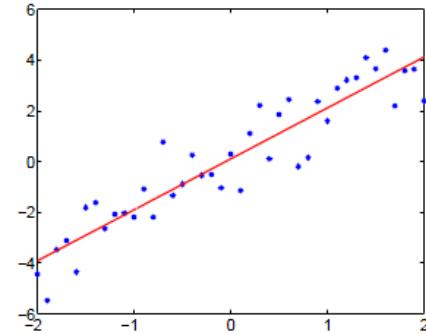
- ▶ Special case:

Observed output = function + noise

$$y = f(\mathbf{x}; \mathbf{w}) + \epsilon$$

e.g.,  $\epsilon \sim N(0, \sigma^2)$

- ▶ Noise: Whatever we cannot capture with our chosen family of functions



# Curve fitting: probabilistic perspective (Example)

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## ► Best regression

$$\mathbb{E}[y|x] = E[f(x; w) + \epsilon] = f(x; w)$$

$$\epsilon \sim N(0, \sigma^2)$$

- $f(x; w)$  is trying to capture the mean of the observations  $y$  given the input  $x$ :
  
- $\mathbb{E}[y|x]$ : conditional expectation of  $y$  given  $x$ 
  - evaluated according to the model (not according to the underlying distribution  $P$ )

# Curve fitting using probabilistic estimation

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- ▶ Maximum Likelihood (ML) estimation
- ▶ Maximum A Posteriori (MAP) estimation
- ▶ Bayesian approach

# Maximum likelihood estimation

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- ▶ Given observations  $\mathcal{D} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^n$
- ▶ Find the parameters that maximize the (conditional) likelihood of the outputs:

$$L(\mathcal{D}; \boldsymbol{\theta}) = p(\mathbf{y}|\mathbf{X}, \boldsymbol{\theta}) = \prod_{i=1}^n p(y^{(i)}|\mathbf{x}^{(i)}, \boldsymbol{\theta})$$

$$\mathbf{y} = \begin{bmatrix} y^{(1)} \\ \vdots \\ y^{(n)} \end{bmatrix} \quad \mathbf{X} = \begin{bmatrix} 1 & x_1^{(1)} & \dots & x_d^{(1)} \\ 1 & x_1^{(2)} & \dots & x_d^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_1^{(n)} & \dots & x_d^{(n)} \end{bmatrix}$$

# Maximum likelihood estimation (Cont'd)

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$$y = f(\mathbf{x}; \mathbf{w}) + \epsilon, \quad \epsilon \sim N(0, \sigma^2)$$

- ▶  $y$  given  $\mathbf{x}$  is normally distributed with mean  $f(\mathbf{x}; \mathbf{w})$  and variance  $\sigma^2$ :
  - ▶ we model the uncertainty in the predictions, not just the mean

$$p(y|\mathbf{x}, \mathbf{w}, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{1}{2\sigma^2}(y - f(\mathbf{x}; \mathbf{w}))^2\right\}$$

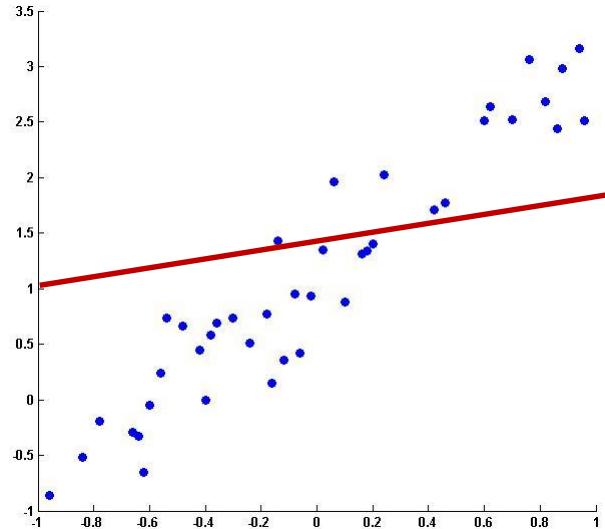
# Maximum likelihood estimation (Cont'd)

- ▶ Example: univariate linear function

$$p(y|x, \mathbf{w}, \sigma^2) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{1}{2\sigma^2}(y - w_0 - w_1x)^2\right\}$$

Why is this line a bad fit according to the likelihood criterion?

$p(y|x, \mathbf{w}, \sigma^2)$  for most of the points will be near zero (as they are far from this line)



# Maximum likelihood estimation (Cont'd)

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- ▶ Maximize the likelihood of the outputs (i.i.d):

$$L(\mathcal{D}; \mathbf{w}, \sigma^2) = \prod_{i=1}^n p(y^{(i)} | \mathbf{x}^{(i)}, \mathbf{w}, \sigma^2)$$

$$\hat{\mathbf{w}} = \operatorname{argmax}_{\mathbf{w}} L(\mathcal{D}; \mathbf{w}, \sigma^2)$$

$$= \operatorname{argmax}_{\mathbf{w}} \prod_{i=1}^n p(y^{(i)} | \mathbf{x}^{(i)}, \mathbf{w}, \sigma^2)$$

# Maximum likelihood estimation (Cont'd)

- ▶ It is often easier (but equivalent) to try to maximize the log-likelihood:

$$\hat{\mathbf{w}} = \operatorname{argmax}_{\mathbf{w}} \ln p(\mathbf{y}|\mathbf{X}, \mathbf{w}, \sigma^2)$$

$$\begin{aligned}\ln \prod_{i=1}^n p(y^{(i)} | \mathbf{x}^{(i)}, \mathbf{w}, \sigma^2) &= \sum_{i=1}^n \ln \mathcal{N}(y^{(i)} | \mathbf{x}^{(i)}, \mathbf{w}, \sigma^2) \\ &= -n \ln \sigma - \frac{n}{2} \ln 2\pi - \frac{1}{2\sigma^2} \sum_{i=1}^n (y^{(i)} - f(\mathbf{x}^{(i)}; \mathbf{w}))^2\end{aligned}$$

  
sum of squares error

# Maximum likelihood estimation (Cont'd)

- ▶ Maximizing log-likelihood (when we assume  $y = f(\mathbf{x}; \mathbf{w}) + \epsilon$ ,  $\epsilon \sim N(0, \sigma^2)$ ) is equivalent to minimizing SSE
- ▶ Let  $\hat{\mathbf{w}}$  be the maximum likelihood (here least squares) setting of the parameters.
- ▶ What is the maximum likelihood estimate of  $\sigma^2$ ?

$$\frac{\partial \log L(\mathcal{D}; \mathbf{w}, \sigma^2)}{\partial \sigma^2} = 0$$
$$\Rightarrow \hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (y^{(i)} - f(\mathbf{x}^{(i)}; \hat{\mathbf{w}}))^2$$

Mean squared prediction error 

# Maximum likelihood estimation (Cont'd)

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- ▶ Generally, maximizing log-likelihood is equivalent to minimizing empirical loss when the loss is defined according to:

$$\text{Loss}\left(y^{(i)}, f(\mathbf{x}^{(i)}, \mathbf{w})\right) = -\ln p(y^{(i)} | \mathbf{x}^{(i)}, \mathbf{w}, \boldsymbol{\theta})$$

- ▶ Loss: negative log-probability
  - ▶ More general distributions for  $p(y|\mathbf{x})$  can be considered

# Maximum A Posterior (MAP) estimation

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- ▶ MAP:
  - ▶ Given observations  $\mathcal{D}$
  - ▶ Find the parameters that maximize the probabilities of the parameters after observing the data (posterior probabilities):

$$\boldsymbol{\theta}_{MAP} = \max_{\boldsymbol{\theta}} p(\boldsymbol{\theta}|\mathcal{D})$$

Since  $p(\boldsymbol{\theta}|\mathcal{D}) \propto p(\mathcal{D}|\boldsymbol{\theta})p(\boldsymbol{\theta})$

$$\boldsymbol{\theta}_{MAP} = \max_{\boldsymbol{\theta}} p(\mathcal{D}|\boldsymbol{\theta})p(\boldsymbol{\theta})$$

# Maximum A Posterior (MAP) estimation

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- Given observations  $\mathcal{D} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^n$

$$\max_{\mathbf{w}} p(\mathbf{w}|\mathbf{X}, \mathbf{y}) \propto p(\mathbf{y}|\mathbf{X}, \mathbf{w})p(\mathbf{w})$$

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{0}, \alpha^2 \mathbf{I}) = \left( \frac{1}{\sqrt{2\pi}\alpha} \right)^{d+1} \exp \left\{ -\frac{1}{2\alpha^2} \mathbf{w}^T \mathbf{w} \right\}$$

# Maximum A Posterior (MAP) estimation

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- Given observations  $\mathcal{D} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^n$

$$\max_{\mathbf{w}} \ln p(\mathbf{y}|\mathbf{X}, \mathbf{w}, \sigma^2) p(\mathbf{w})$$

$$\min_{\mathbf{w}} \frac{1}{\sigma^2} \sum_{i=1}^n (y^{(i)} - f(\mathbf{x}^{(i)}; \mathbf{w}))^2 + \frac{1}{\alpha^2} \mathbf{w}^T \mathbf{w}$$

- Equivalent to regularized SSE with  $\lambda = \frac{\sigma^2}{\alpha^2}$

# Bayesian approach

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- ▶ Given observations  $\mathcal{D} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^n$
- ▶ Find the parameters that maximize the probabilities of observations

$$p(y|\mathbf{x}, \mathcal{D}) = \int p(y|\mathbf{w}, \mathbf{x})p(\mathbf{w}|\mathcal{D})d\mathbf{w}$$

- ▶ Example of prior distribution

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{0}, \alpha^2 \mathbf{I})$$

# Bayesian approach

- ▶ Given observations  $\mathcal{D} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^N$
- ▶ Find the parameters that maximize the probabilities of observations

$$p(\mathcal{D}|\mathbf{w}) = L(\mathcal{D}; \mathbf{w}, \boldsymbol{\theta}) = \prod_{i=1}^N p(y^{(i)} | \mathbf{w}^T \mathbf{x}^{(i)}, \boldsymbol{\theta})$$
$$p(y^{(i)} | f(\mathbf{x}^{(i)}, \mathbf{w}), \boldsymbol{\theta}) = \mathcal{N}(y^{(i)} | \mathbf{w}^T \mathbf{x}^{(i)}, \sigma^2)$$

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{0}, \alpha^2 \mathbf{I})$$

$$p(\mathbf{w}|\mathcal{D}) \propto p(\mathcal{D}|\mathbf{w})p(\mathbf{w})$$

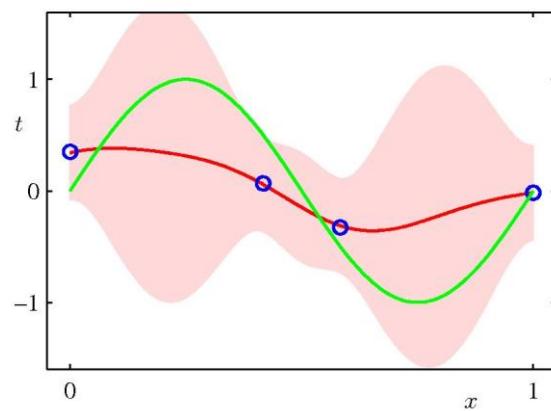
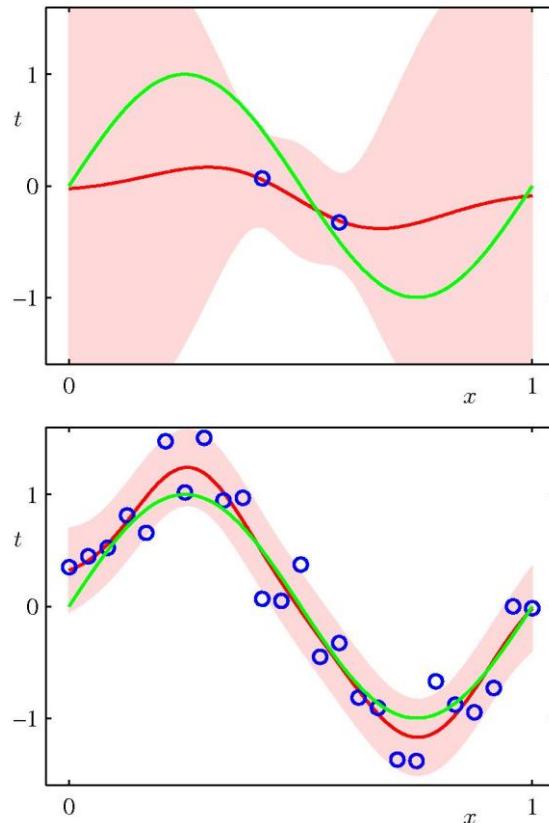
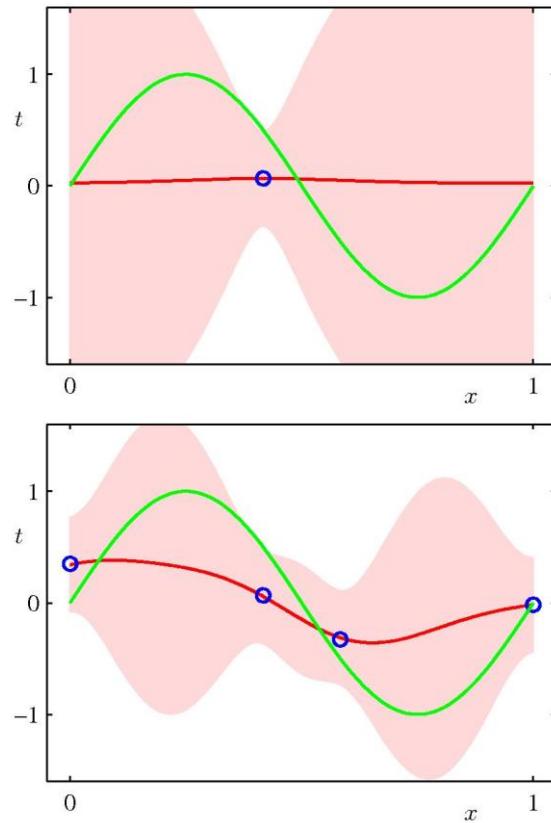
Predictive distribution

$$p(y|\mathbf{x}, \mathcal{D}) = \int p(y|\mathbf{w}, \mathbf{x})p(\mathbf{w}|\mathcal{D})d\mathbf{w}$$

$$p(y|\mathbf{x}, \mathcal{D}) = N(\mathbf{m}_N^T \mathbf{x}, \sigma_N^2(\mathbf{x}))$$

# Predictive distribution: example

- ▶ Example: Sinusoidal data, 9 Gaussian basis functions



Red curve shows the mean of the predictive distribution  
Pink region spans one standard deviation either side of the mean



# Predictive distribution: example

- ▶ Functions whose parameters are sampled from  $p(w|\mathcal{D})$

